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图书基本信息

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内容概要

The 0bjectectives off STECH'06 , the Fourth International Symposium oit Speed—up and ServiceTechnology for Railway andMaglev Systems , which held on July 13—16 of2006inChangdu , China , are to present and discuss the state 0f the ard Of the scientific and technical aspects of high speed and heavy haul railways , maglev and urban transportation systams Recent years the railways in China have been developed rapidly The total railway line length has exceeded 70 , 000km Several times for the raising speeds of trains have been carried out and the speed 0n the main lines has reached 140 to 160 km / h This year the train speed will further reach to 200km / h , and several high speed fines with speed from 200 to 350km / h are under construction The maglev trains aresuccessfully operating in Shanghai.



书籍目录

Invited PaperHigh-speed Train Dynamic Environment and Its Impact Assessment Assessment Zhiyun ShenSiytgwest Jiaotong University, ChinaAdvanced Control and Monitoring for Railway Vehicle SuspensionsRoger Goodall, TXMeiLoughborough University, UKCollaborative Research for Railway Vehicle Systems Possibility of Innovative and Attractive SystemYoshihiro SudaThe University of Tokyo, Tokyo, Japan VehicleOn the Application of Autonomy to Railway Vehicle's Assembly GroupsJohannes Gregor, Arne Berger, Torsten DellmannDynamic Problems in Developing Bogies for Wagons with Increased CapacityYu, Boronenko, A.Orlova, E.RudakovaSliding Mode Control of Wheel Slip Prevention with Robust Variable Structure System OBserver for Railway VehiclesHiro-o Yamazaki, Takanori Obara, Takayoshi Kamada, Masao NagaiDynamic Simulation of Railway Train BrakingRen Luo, Jing ZengStudy on Coupled Characteristic of Coupled Wheelset Maoru Chi, Weihua Zhang, Jing Zeng, Huanyun Dai, Pingbo WuActive Vibration Control of Elastic Vehicle Body with Smart StructureTakayuki Tohtake, Masao Nagai, Takayoshi Kamada and Hidehisa Yoshida……InfrastructureBoundary ProblemEnvironment and EnergySafety Technology and Accident AnalysisUrban TransportationMaglev and Linear Motor Drive TechnologyOperation Managment and MaintenanceIntelligent Transportation SystemOther Topics



章节摘录

For easy experiments for lateral dynamics, the traction device with actuator outside of the vehicle is adopted. The traction system, which consists of a gantry robot actuated with AC motor and a linear guide lies parallel to the straight track, works to keep the vehicle with desired velocity along the straight section. The patterns of vehicle velocity on this straight track are suitably controlloed by the servo control up to 3.0 m/s. The vehicle is released from the traction system after gaining the desired velocity at the end of the straight track, and then runs into curved track by means of its applied initial velocity. transition curve is sinusoidal transition curve and the radius of constant curve is 3.3m. The rail cant is freely changed by the adjustable cant mechanism. In the curved section, gradient (13%) is given so that the model vehicle should not stop on the cured track owing to the resistant force generated by flange contact force of wheel. As for thye ground measurement system, the system with strain gauge and strain meter is adopted to measure the vertical and lateral forces of rails. Using the measuring system is able to set at any point on the track only changing the position of strain gauges. & hellip; & hellip;



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