<<约束力学系统动力学>>

图书基本信息

书名:<<约束力学系统动力学>>

13位ISBN编号: 9787564021689

10位ISBN编号:7564021683

出版时间:2009-4

出版时间:北京理工大学出版社

作者:梅凤翔,吴惠彬 著

页数:604

版权说明:本站所提供下载的PDF图书仅提供预览和简介,请支持正版图书。

更多资源请访问:http://www.tushu007.com

<<约束力学系统动力学>>

前言

This book is entitled Dynamics of Constrained Mechanical Systems. The constrained mechanical systems, in my opinion, contain the three kinds of the systems, i.e. the holonomic systems, the nonholonomic systems and the Birkhoff systems. The book covers the following six parts.Part I Fundamental Concepts in Constrained Mechanical Systems. The part has 6 chapters: Constraints and their classification, Generalized coordinates, Quasi-velocities and quasicoordinates, Virtual displacements, Ideal constraints, Transpositional relations of differential and variational operators. Part II Variational Principles in Constrained Mechanical Systems. It covers 5 chapters: Differential variational principles, Integral variational principles in terms of generalized coordinates for holonomic systems, Integral variational principles in terms of quasi-coordinates for holonomic systems, Integral variational principles for nonholonomic systems, Pfaff-Birkhoff principle. Part III Differential Equations of Motion of Constrained Mechanical Systems. It covers 11 chapters: Lagrange equations of holonomic systems, Lagrange equations with multiplier for nonholonomic systems, Mac Millan equations for nonholonomic systems, Volterra equations for nonholonomic systems, Chaplygin equations for nonholonomic systems, Boltzmann-Hamel equations for nonholonomic systems, Euler-Lagrange equations for higher order honholonomic systems, Nielsen equations, Appell equations, Equations of motion of mixed type, Canonical equations. Part IV Special Problems in Constrained Mechanical Systems. It covers 8 chapters: Stability of motion and theory of small oscillations, Dynamics of rigid body with fixed point, Dynamics of relative motion, Dynamics of controllable mechanical systems, Dynamics of impulsive motion, Dynamics of variable mass systems, Dynamics of electromechanical systems, Dynamics in event space. Part V Integration Methods in Constrained Mechanical Systems. It covers 6 chapters: Methods of reduction of order, Dynamics algebra and Poisson method, Canonical transformations, Hamilton-Jacobi method, Field method, Integral invariants. Part VI Symmetries and Conserved Quantities in Constrained Mechanical Systems. The part has 10 chapters: Noether symmetries and conserved quantities, Lie symmetries and Hojman conserved quantities, Form invariance and new conserved quantities, Noether symmetries and Hojman conserved quantities, Noether symmetries and new conserved quantities, Lie symmetries and Noether conserved quantities~ Lie symmetries and new conserved quantities, Form invariance and Noether conserved quantities, Form invariance and Hojman conserved quantities, Unified symmetries and conserved quantities.

<<约束力学系统动力学>>

内容概要

本书系统地阐述了约束力学系统的变分原理、运动方程、相关专门问题的理论与应用、积分方法、对称性与守恒量等内容,具有很高的学术价值,为方便国际学术交流,译成英文出版。

全书共分为六个部分: 第一部分:约束力学系统的基本概念。

本部分包含6章,介绍分析力学的主要基本概念;第二部分:约束力学系统的变分原理。

本部分有5章,阐述微分变分原理、积分变分原理以及Pfaff-Birkhoff原理;第三部分:约束力学系统的运动微分方程。

本部分共11章,系统介绍完整系统、非完整系统的各类运动方程;第四部分:约束力学系统的专门问 题。

本部分有8章,讨论运动稳定性和微扰理论、刚体定点转动、相对运动动力学、可控力学系统动力学、打击运动动力学、变质量系统动力学、机电系统动力学、事件空间动力学等内容;第五部分:约束力学系统的积分方法。

本部分有6章,介绍降阶方法、动力学代数与Poisson方法、正则变换、Hamilton-Jacobi方法、场方法、积分不变量;第六部分:约束力学系统的对称性与守恒量。

本部分共10章,讨论Noether对称性、Lie对称性、形式不变性,以及由它们导致的各种守恒量。 本书的出版必将引起国内外同行的关注,对该领域的发展将起到重要的推动作用。

<<约束力学系统动力学>>

作者简介

Mei Fengxiang (1938-), a native of Shenyang, China, and a graduate of the Department of Mathematics and Mechanics of Peking University (in 1963) and Ecole Nationalle Superiere de M6canique (Docteur d'Etat, 1982), has been teaching theoretical mechanics, analytical mechanics, dynamics of nonholonomic systems, stability of motion, and applications of Lie groups and Lie algebras to constrained mechanical systems at Beijing Institute of Technology. His research interests are in the areas of dynamics of constrained systems and mathematical methods in mechanics. He currently directs 12 doctoral candidates. He was a visiting professor at ENSM (1981-1982) and Universit LAVAL (1994). Mei has authored over 300 research papers and is the author of the following 10 books (in Chinese): Foundations of Mechanics of Nonholonomic Systems (1985); Researches on Nonholonomic Dynamics (1987); Foundations of Analytical Mechanics (1987); Special Problems in Analytical Mechanics (1988); Mechanics of Variable Mass Systems (1989); Advanced Analytical Mechanics (1991); Dynamics of Birkhoffian System (1996); Stability of Motion of Constrained Mechanical Systems (1997); Symmetries and Invariants of Mechanical Systems (1999); and Applications of Lie Groups and Lie Algebras to Constrained Mechanical Systems (1999).

<<约束力学系统动力学>>

书籍目录

Fundamental Concepts in Constrained Mechanical Systems 1 Constraints and Their Classification 1.1 1.2 Equations of Constraint 1.3 Classification of Constraints 1.3.1 Holonomic Constraints Constraints and Nonholonomic Constraints 1.3.2 Stationary Constraints and Non-stationary Constraints 1.3.3 Unilateral Constraints and Bilateral Constraints 1.3.4 Passive Constraints and Active Constraints 1.4 Integrability Theorem of Differential Constraints 1.5 Generalization of the Concept of Constraints 1.5.1 First Integral as Nonholonomic Constraints 1.5.2 Controllable System as Holonomic or Nonholonomic 1.5.4 Restriction on Change of Dynamical System 1.5.3 Nonholonomic Constraints of Higher Order Properties as Constraint 1.6 Remarks 2 Generalized Coordinates 2.1 Generalized Coordinates Generalized Velocities 2.3 Generalized Accelerations 2.4 Expression of Equations of Nonholonomic Constraints in Terms of Generalized Coordinates and Generalized Velocities 2.5 Remarks 3 Quasi-Velocities and Quasi-Coordinates 3.1 Quasi-Velocities 3.2 Quasi-Coordinates 3.3 Quasi-Accelerations Remarks 4 Virtual Displacements 4.1 Virtual Displacements 4.1.1 Concept of Virtual Displacements 4.1.2 Condition of Constraints Exerted on Virtual Displacements 4.1.3 Degree of Freedom 4.2 Necessary and Sufficient Condition Under Which Actual Displacement Is One of Virtual Displacements 4.3 Generalization of the Concept of Virtual Displacement 4.4 Remarks 5 Ideal Constraints 5.1 Constraint Reactions 5.2 Examples of Ideal Constraints 5.3 Importance and Possibility of Hypothesis of Ideal 5.4 Remarks 6 Transpositional Relations of Differential and Variational Operations Constraints Transpositional Relations for First Order Nonholonomic Systems 6.1.1 Transpositional Relations in Terms of **Generalized Coordinates** 6.1.2 Transpositional Relations in Terms of Quasi-Coordinates 6.2 Transpositional Relations of Higher Order Nonholonomic Systems 6.2.1 Transpositional Relations in Terms 6.2.2 Transpositional Relations in Terms of Quasi-Coordinates of Generalized Coordinates 6.3 Vujanovic Transpositional Relations 6.3.1 Transpositional Relations for Holonomic Nonconservative Systems Transpositional Relations for Nonholonomic Systems Variational Principles in Constrained 6.4 Remarks Mechanical Systems 7 Differential Variational Principles 7.1 D'Alembert-Lagrange Principle Differential Equations of Motion of Constrained Mechanical Systems Special Problems in Constrained Mechanical Systems Integration Methods in Constrained Mechanical Systems Symmetries and Conserved Quantities in Constrained Mechanical Systems

<<约束力学系统动力学>>

章节摘录

插图:

<<约束力学系统动力学>>

编辑推荐

《约束力学系统动力学(英文版)》共分46个章节,主要对约束力学系统的变分原理、运动方程、相关专门问题的理论与应用、积分方法、对称性与守恒量等内容作了系统地阐述。 该书可供各大专院校作为教材使用,也可供从事相关工作的人员作为参考用书使用。

<<约束力学系统动力学>>

版权说明

本站所提供下载的PDF图书仅提供预览和简介,请支持正版图书。

更多资源请访问:http://www.tushu007.com